NONLINEAR FRACTIONAL SCHRÖDINGER EQUATIONS COUPLED BY POWER-TYPE NONLINEARITIES

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ABSTRACT. In this work we study the following class of systems of coupled nonlinear fractional Schrödinger equations,

$$\begin{cases} (-\Delta)^{s} u_{1} + \lambda_{1} u_{1} = \mu_{1} |u_{1}|^{2p-2} u_{1} + \beta |u_{2}|^{p} |u_{1}|^{p-2} u_{1} & \text{in } \mathbb{R}^{N}, \\ (-\Delta)^{s} u_{2} + \lambda_{2} u_{2} = \mu_{2} |u_{2}|^{2p-2} u_{2} + \beta |u_{1}|^{p} |u_{2}|^{p-2} u_{2} & \text{in } \mathbb{R}^{N}, \end{cases}$$

where $u_1, u_2 \in W^{s,2}(\mathbb{R}^N)$, with $N = 1, 2, 3; \lambda_j, \mu_j > 0, j = 1, 2, \beta \in \mathbb{R}, p \ge 2$ and $\frac{p-1}{2p}N < s < 1$. We prove the existence of positive radial bound and ground state solutions provided the parameters $\beta, p, \lambda_j, \mu_j$, (j = 1, 2) satisfy appropriate conditions. We also study the previous system with *m*-equations,

$$(-\Delta)^{s} u_{j} + \lambda_{j} u_{j} = \mu_{j} |u_{j}|^{2p-2} u_{j} + \sum_{\substack{k=1\\k\neq j}}^{m} \beta_{jk} |u_{k}|^{p} |u_{j}|^{p-2} u_{j}, \quad u_{j} \in W^{s,2}(\mathbb{R}^{N}); \ j = 1, \dots, m$$

where $\lambda_j, \mu_j > 0$ for $j = 1, ..., m \ge 3$, the coupling parameters $\beta_{jk} = \beta_{kj} \in \mathbb{R}$ for $j, k = 1, ..., m, j \ne k$. We prove similar results as for m = 2, depending on the values of the parameters $p, \beta_{jk}, \lambda_j, \mu_j$.

INTRODUCTION

In this work we study the existence of positive solutions to the following system of coupled nonlinear fractional Schrödinger (NLFS) equations,

(1)
$$\begin{cases} (-\Delta)^{s} u_{1} + \lambda_{1} u_{1} = \mu_{1} |u_{1}|^{2p-2} u_{1} + \beta |u_{2}|^{p} |u_{1}|^{p-2} u_{1} & \text{in } \mathbb{R}^{N}, \\ (-\Delta)^{s} u_{2} + \lambda_{2} u_{2} = \mu_{2} |u_{2}|^{2p-2} u_{2} + \beta |u_{1}|^{p} |u_{2}|^{p-2} u_{2} & \text{in } \mathbb{R}^{N}, \end{cases}$$

where $u_j \in W^{s,2}(\mathbb{R}^N)$ with $N = 1, 2, 3; \lambda_j, \mu_j > 0$ for j = 1, 2, the coupling factor $\beta \in \mathbb{R}$, $p \ge 2$ and $\frac{p-1}{2p}N < s < 1$. We also study the previous system with *m*-equations,

(2)
$$(-\Delta)^{s} u_{j} + \lambda_{j} u_{j} = \mu_{j} |u_{j}|^{2p-2} u_{j} + \sum_{\substack{k=1\\k \neq j}}^{m} \beta_{jk} |u_{k}|^{p} |u_{j}|^{p-2} u_{j},$$

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with $u_j \in W^{s,2}(\mathbb{R}^N)$, λ_j , $\mu_j > 0$, $j = 1, \ldots, m \ge 3$, the coupling parameters $\beta_{jk} = \beta_{kj} \in \mathbb{R}$ for $j, k = 1, \ldots, m, j \ne k$. We prove similar results as for (1), depending on the values of the parameters $p, \beta_{jk}, \lambda_j, \mu_j$.

Problems like (1) have been widely investigated with the classical Laplacian (s = 1) in the last years so it is complicated to give a complete list of references. We refer, among others, to [2, 3, 5, 6, 11, 13, 15, 16, 18, 24, 25, 26, 29, 30, 32, 34, 36, 37] and references therein. It is well known that solutions of (1), at least for the classical case s = 1, are related to the solitary waves of the Gross-Pitaevskii equations, which have applications in many physical models, such as in nonlinear optics (cf. [1, 27, 28]) and in multi-species Bose-Einstein condensates (cf. [10, 31]). Actually, a planar light beam propagating in the z direction in a non-linear medium, can be described by a vector NLS equation like

$$i\mathbf{E}_z + \mathbf{E}_{xx} + \kappa |\mathbf{E}|^2 \mathbf{E} = 0,$$

where i, $\mathbf{E}(x, z)$ denote the imaginary unit and the complex envelope of an Electric field, respectively. If \mathbf{E} is the sum of two right- and left-hand polarized waves a_1E_1 and a_2E_2 , $a_j \in \mathbb{R}$, then, assuming $\kappa = 1$, solitary wave solutions $E_j(z, x) = e^{i\lambda_j z} u_j(x)$, where $\lambda_j > 0$ and $u_j(x)$ are real valued functions, provide us with the system

(3)
$$\begin{cases} -u_1'' + \lambda_1 u_1 = (a_1^2 u_1^2 + a_2^2 u_2^2) u_1, \\ -u_2'' + \lambda_2 u_2 = (a_1^2 u_1^2 + a_2^2 u_2^2) u_2. \end{cases}$$

If we take the coupling factor $a_1^2 = a_2^2 := \beta$ as a parameter and let the coefficients of u_j^3 , namely $\mu_j > 0$, to be different, then (3) corresponds to (1) with N = 1, s = 1 and p = 2. Similarly, looking for solitary wave solutions for the NLFS equation in \mathbb{R}^N ,

$$i \mathbf{E}_z - (-\Delta)^s \mathbf{E} + \kappa |\mathbf{E}|^2 \mathbf{E} = 0,$$

one arrives to system (1) with p = 2. We point out that this type of nonlocal diffusion involving the fractional Laplacian $(-\Delta)^s$ arises in several physical phenomena like flames propagation and chemical reactions, population dynamics, geophysical fluid dynamics, as well as in probability, American option in finance or in α -stable Lévy processes (with $\alpha = 2s$) (cf. [4, 7, 14, 35]). Here we are interested in systems of coupled NLFS equations involving the so called fractional Schrödinger operator, $(-\Delta)^s + \lambda \operatorname{Id}$, (cf. [17, 22, 23]).

Our main aim is then to give a classification of positive solutions of (1) and also for the system with *m*-equations (2). Precisely, we will prove the following.

-Existence of positive radial ground states under the following hypotheses:

- p = 2 and the coupling coefficient $\beta > \Lambda'$; see Theorem 3.2,
- $p \ge 2$ and the coupling coefficient β satisfying hypothesis (\mathcal{H}); see Theorem 4.3.

-Existence of radial bound states when:

- p = 2 and $\beta < \Lambda$; see Theorem 3.3-(i) which are positive provided $\beta > 0$,
- p > 2 and $\beta \in \mathbb{R}$; see Theorem 3.3-(*ii*), which are positive when $\beta > 0$,
- $p \ge 2$ and $\beta \sim 0$; see Theorem 3.3-(*iii*) and Theorem 4.4. The radial bound states are positive for $\beta > 0$. We also prove a bifurcation result.

1. Preliminaries and Notation

Given 0 < s < 1, the nonlocal operator $(-\Delta)^s$ in \mathbb{R}^N is defined on the Schwartz class of functions $g \in \mathcal{S}$ through the Fourier transform,

$$[(-\Delta)^s g]^{\wedge}(\xi) = (2\pi |\xi|)^{2s} \,\widehat{g}(\xi),$$

or via the Riesz potential, (cf. [21, 33]). Observe that s = 1 corresponds to the classical Laplacian. There is another way of defining this operator. In fact, for $s = \frac{1}{2}$, the square root of the Laplacian acting on a function u in the whole space \mathbb{R}^N , can be calculated as the normal derivative of its harmonic extension to the upper half-space \mathbb{R}^{N+1}_+ , this is so-called Dirichlet to Neumann operator. Based on this idea, Caffarelli and Silvestre (cf. [9]) proved that $(-\Delta)^s$ can be realized in a local way by using the s-harmonic extension.

More precisely, given u a regular function in \mathbb{R}^N , we define its *s*-harmonic extension to the upper half-space \mathbb{R}^{N+1}_+ , denoted by $w = E_s[u]$, as the solution to the problem

$$\begin{cases} -\operatorname{div}(y^{1-2s}\nabla w) = 0 & \text{ in } \mathbb{R}^{N+1}_+, \\ w = u & \text{ on } \mathbb{R}^N \times \{y = 0\} \end{cases}$$

The key point of the s-harmonic extension comes from the following identity (cf. [9]),

$$-\kappa_s \lim_{y \to 0^+} y^{1-2s} \frac{\partial w}{\partial y}(x,y) = (-\Delta)^s u(x),$$

with $\kappa_s = 2^{2s-1} \frac{\Gamma(s)}{\Gamma(1-s)}$. The above Dirichlet-Neumann procedure provides a formula for the fractional Laplacian in \mathbb{R}^N , equivalent to that obtained using the Fourier transform. In this case, the s-harmonic extension and the fractional Laplacian have explicit expressions in terms of the Poisson and the Riesz kernels respectively (cf. [8]),

$$w(x,y) = c_{N,s} y^{2s} \int_{\mathbb{R}^N} \frac{u(z)}{(|x-z|^2+y^2)^{\frac{N+2s}{2}}} dz, \qquad (-\Delta)^s u(x) = d_{N,s} \int_{\mathbb{R}^N} \frac{u(x) - u(y)}{|x-y|^{N+2s}} dy.$$

The appropriate functional spaces to work with are the Sobolev spaces $\dot{H}^{s}(\mathbb{R}^{N})$ and $X^{s}(\mathbb{R}^{N+1})$, defined as the completion of $\mathcal{C}_0^{\infty}(\mathbb{R}^N)$ and $\mathcal{C}_0^{\infty}(\overline{\mathbb{R}^{N+1}_+})$ respectively, under the norms

$$\|\psi\|_{\dot{H}^{s}}^{2} = \int_{\mathbb{R}^{N}} |(-\Delta)^{\frac{s}{2}} \psi(x)|^{2} dx, \qquad \|\phi\|_{X^{s}}^{2} = \kappa_{s} \int_{\mathbb{R}^{N+1}_{+}} y^{1-2s} |\nabla\phi(x,y)|^{2} dx dy.$$

The extension operator $E_s : \dot{H}^s(\mathbb{R}^N) \to X^s(\mathbb{R}^{N+1}_+), u \mapsto w = E_s[u]$, is an isometry between $\dot{H}^s(\mathbb{R}^N)$ and $X^s(\mathbb{R}^{N+1}_+)$, that is, $\|\varphi\|_{\dot{H}^s} = \|E_s[\varphi]\|_{X^s}$ for all $\varphi \in \dot{H}^s(\mathbb{R}^N)$. Moreover, there exists C = C(N, s) > 0 such that (cf. [8]), $\|w(\cdot, 0)\|_{L^{2^*_s}} \leq C \|w\|_{X^s}$ for all $w \in X^s(\mathbb{R}^{N+1}_+)$.

Along the work we will use the following notation:

• $E := W^{s,2}(\mathbb{R}^N)$, denotes the fractional Sobolev space with scalar product and norm

$$(u \mid v)_j = \int_{\mathbb{R}^N} [(-\Delta)^{\frac{s}{2}} u (-\Delta)^{\frac{s}{2}} v + \lambda_j u v] dx, \quad \|u\|_j^2 = (u \mid u)_j, \ j = 1, 2.$$

- $\mathbb{E} := E \times E$; the elements in \mathbb{E} will be denoted by $\mathbf{u} = (u_1, u_2)$; as a norm in \mathbb{E} we will take $\|\mathbf{u}\|_{\mathbb{E}}^2 = \|u_1\|_1^2 + \|u_2\|_2^2$.
- for $\mathbf{u} \in \mathbb{E}$, $\mathbf{u} \ge \mathbf{0}$ (resp. $\mathbf{u} > \mathbf{0}$) means that $u_j \ge 0$, (resp. $u_j > 0$), for all j = 1, 2.

For $u \in E$, (resp. $\mathbf{u} \in \mathbb{E}$), we set

$$F(\mathbf{u}) = \frac{1}{2p} \int_{\mathbb{R}^N} \mu_1 |u_1|^{2p} + \mu_2 |u_2|^{2p} dx, \qquad G(\mathbf{u}) = \frac{1}{p} \int_{\mathbb{R}^N} |u_1|^p |u_2|^p dx,$$
$$I_j(u) = \frac{1}{2} ||u||_j^2 - \frac{1}{2p} \mu_j \int_{\mathbb{R}^N} |u|^{2p} dx, \qquad \Phi(\mathbf{u}) = \frac{1}{2} ||\mathbf{u}||_{\mathbb{E}}^2 - F(\mathbf{u}) - \beta G(\mathbf{u})$$

We remark that F and G are well defined because $\frac{p-1}{2p}N < s < 1$ guarantees $2p < 2_s^*$ which in turn implies the continuous Sobolev embedding $E \hookrightarrow L^{2p}(\mathbb{R}^N)$.

Any critical point $\mathbf{u} \in \mathbb{E}$ of Φ gives rise to a solution of (1). If $\mathbf{u} \neq \mathbf{0}$ we say that such a critical point is non-trivial. We also say that a solution \mathbf{u} of (1) is *positive* if $\mathbf{u} > \mathbf{0}$.

Definition 1.1. We say $\mathbf{u} = (u_1, u_2) \in \mathbb{E}$ is a *bound state* to (1) iff it is a critical point of Φ .

Definition 1.2. A positive bound state $\mathbf{u} > \mathbf{0}$ is called a *ground state* of (1) if its energy is minimal among *all the non-trivial bound states*, namely

$$\Phi(\mathbf{u})=\min\{\mathbf{\Phi}(\mathbf{v}):\mathbf{v}\in\mathbb{E}\setminus\{\mathbf{0}\},\;\mathbf{\Phi}'(\mathbf{v})=\mathbf{0}\}.$$

Ground states are candidates to be orbitally stable for evolution equations (cf. [12]).

2. The Nehari manifold and preliminary results

To find critical points of Φ we will use the so-called Nehari manifold approach. Let us set $\Psi(\mathbf{u}) = (\Phi'(\mathbf{u}) \mid \mathbf{u}) = \|\mathbf{u}\|_{\mathbb{E}}^2 - 2p F(\mathbf{u}) - 2p\beta G(\mathbf{u})$, then, we define the Nehari manifold as

$$\mathcal{M} = \{ \mathbf{u} \in \mathbb{E}_{rad} \setminus \{ \mathbf{0} \} : \Psi(\mathbf{u}) = 0 \},\$$

where *rad* means radial. Plainly, \mathcal{M} contains all the non-trivial critical points of Φ on \mathbb{E}_{rad} .

Proposition 2.1. We have that $\mathbf{u} \in \mathbb{E}$ is a non-trivial critical point of Φ if and only if $\mathbf{u} \in \mathcal{M}$ and is a critical point of Φ constrained to \mathcal{M} .

Consequently, \mathcal{M} is called a *natural constraint* for Φ . The key point of the Nehari manifold approach is that Φ is bounded from below on \mathcal{M} so that one can try to minimize Φ on \mathcal{M} .

Concerning the Palais-Smale (PS) condition, for N = 1, we have no compact embedding of E into $L^q(\mathbb{R})$ for any $1 < q < 2_s^*$. Nevertheless, we will prove that for a given PS sequence we can find a subsequence its weak limit is a bound state. By the compact embeddings in the radial case, for $1 < N \leq 3$ the PS condition follows by a standard argument.

Lemma 2.2. Assume $1 < N \leq 3$. Then Φ satisfies the (PS) condition on \mathcal{M} : every $\mathbf{u}_n \in \mathcal{M}$ such that $\Phi(\mathbf{u}_n) \to c$ and $\nabla_{\mathcal{M}} \Phi(\mathbf{u}_n) \to 0$ has a strongly convergent subsequence.

Next, we need some existence results for the decoupled equations that allow us to state the character as critical points of the semi-trivial solutions. To that end, we recall that

(4)
$$(-\Delta)^s u + u = |u|^{\alpha} u \quad \text{in } \mathbb{R}^N, \quad u \in E, \quad u \neq 0,$$

has a unique radial positive solution (cf. [19, 20]) for $0 < \alpha < \frac{4s}{N-2s}$. It is clear that, for any $\beta \in \mathbb{R}$, system (1) has two semi-trivial positive solutions, $\mathbf{u}_1 = (U_1, 0)$ and $\mathbf{u}_2 = (0, U_2)$, where U_j is the unique radial positive solution of

(5)
$$(-\Delta)^s u + \lambda_j u = \mu_j |u|^{2p-2} u.$$

Thus, if we set $U_j(x) = \left(\frac{\lambda_j}{\mu_j}\right)^{\frac{1}{2p-2}} U(\lambda_j^{\frac{1}{2s}} x)$, j = 1, 2, with U the unique positive radial solution of (4), then U_j are solutions of (5). Hence, to find non-trivial solutions, one has to find solutions having *both components* not identically zero.

We are ready to show existence of non-negative solutions of (1) different from \mathbf{u}_j , j = 1, 2. Let us define $\Lambda = \min\{\gamma_{12}, \gamma_{21}\}$ and $\Lambda' = \max\{\gamma_{12}, \gamma_{21}\}$ where

$$\gamma_{12} = \inf_{\varphi \in E_{rad} \setminus \{0\}} \frac{\|\varphi\|_2^2}{\int_{\mathbb{R}^N} U_1^2 \varphi^2 dx}, \qquad \gamma_{21} = \inf_{\varphi \in E_{rad} \setminus \{0\}} \frac{\|\varphi\|_1^2}{\int_{\mathbb{R}^N} U_2^2 \varphi^2 dx}.$$

The existence of nontrivial nonnegative solutions to (1) relies on the next result.

Proposition 2.3. The following holds:

- (1) If p = 2, then
 - (i) for any $\beta < \Lambda$, the semi-trivial solutions \mathbf{u}_j , are strict local minima of $\Phi|_{\mathcal{M}}$.
 - (ii) for any $\beta > \Lambda'$, the semi-trivial solutions \mathbf{u}_j , j = 1, 2, are saddle points of $\Phi|_{\mathcal{M}}$. In particular, we have $\inf_{\mathcal{M}} \Phi < \min\{\Phi(\mathbf{u}_1), \Phi(\mathbf{u}_2)\}$.
- (2) If p > 2, for any $\beta \in \mathbb{R}$, the semi-trivial solutions \mathbf{u}_j are strict local minima of $\Phi|_{\mathcal{M}}$.

3. Existence Results

By Proposition 2.1, to find a non-trivial solution of (1) it is enough to find a critical point of $\Phi|_{\mathcal{M}}$. This will follow from Proposition 2.3 and the PS condition (Lemma 2.2 if N = 2, 3).

Proposition 3.1. The following holds:

- (1) If p = 2,
 - (i) for any $\beta < \Lambda$, the functional Φ has a Mountain-Pass (MP) critical point \mathbf{u}^* on \mathcal{M} . Moreover, one has $\Phi(\mathbf{u}^*) > \max\{\Phi(\mathbf{u}_1), \Phi(\mathbf{u}_2)\}$.
 - (ii) for any $\beta > \Lambda'$, the functional Φ has a global minimum $\widetilde{\mathbf{u}}$ on \mathcal{M} . Moreover, one has $\Phi(\widetilde{\mathbf{u}}) < \min\{\Phi(\mathbf{u}_1), \Phi(\mathbf{u}_2)\}$.
- (2) If p > 2, for any $\beta \in \mathbb{R}$ the functional Φ has a MP critical point \mathbf{u}^* on \mathcal{M} . Moreover, one has $\Phi(\mathbf{u}^*) > \max\{\Phi(\mathbf{u}_1), \Phi(\mathbf{u}_2)\}$.

3.1. Existence of ground states. This result relies on Proposition 3.1–(1)-(*ii*), providing a MP critical point $\tilde{\mathbf{u}}$ with $\Phi(\tilde{\mathbf{u}}) < \min\{\Phi(\mathbf{u}_1), \Phi(\mathbf{u}_2)\}$, which will lead to a ground state.

Theorem 3.2. If p = 2 and $\beta > \Lambda'$, system (1) has a positive radial ground state $\widetilde{\mathbf{u}}$.

3.2. Existence of bound states. Proposition 3.1–(1)-(*i*), –(2)-(*i*) provide MP critical points with energy greater than max{ $\Phi(\mathbf{u}_1), \Phi(\mathbf{u}_2)$ } and, hence, will not lead a ground state. The restriction $\beta > 0$ arises naturally in order to apply the strong maximum principle.

Theorem 3.3. The following holds:

- (i) Assuming p = 2 and $\beta < \Lambda$, the system (1) has a radial bound state \mathbf{u}^* such that $\mathbf{u}^* \neq \mathbf{u}_j$, j = 1, 2. Moreover, if $0 < \beta < \Lambda$, then $\mathbf{u}^* > 0$.
- (ii) Assuming p > 2 and $\beta \in \mathbb{R}$, the system (1) has a radial bound state \mathbf{u}^* such that $\mathbf{u}^* \neq \mathbf{u}_j, j = 1, 2$. Moreover, if $\beta > 0$, then $\mathbf{u}^* > 0$.
- (iii) If $p \ge 2$ and $\beta = \varepsilon b$ and $|\varepsilon|$ small enough, then system (1) has a radial bound state $\mathbf{u}_{\varepsilon}^*$ such that $\mathbf{u}_{\varepsilon}^* \to \mathbf{z} := (U_1, U_2)$ as $\varepsilon \to 0$. Moreover, if $\beta = \varepsilon b > 0$ then $\mathbf{u}_{\varepsilon}^* > \mathbf{0}$.

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4. Some results for systems with more than 2 equations

The above arguments allow us to prove weaker existence results for systems with $m \geq 3$ equations, indeed to prove existence of *nonnegative* bound and ground state solutions. However, following [25] and [3], we will prove the existence of *positive* radial ground and bound states respectively. To simplify, we start showing the results for the system

(6)
$$\begin{cases} (-\Delta)^{s}u_{1} + \lambda_{1}u_{1} = \mu_{1}|u_{1}|^{2p-2}u_{1} + \beta_{12}|u_{2}|^{p}|u_{1}|^{p-2}u_{1} + \beta_{13}|u_{3}|^{p}|u_{1}|^{p-2}u_{1} + \beta_{13}|u_{3}|^{p}|u_{2}|^{p-2}u_{1} + \beta_{12}|u_{1}|^{p}|u_{2}|^{p-2}u_{2} + \beta_{23}|u_{3}|^{p}|u_{2}|^{p-2}u_{2} + \beta_{23}|u_{3}|^{p}|u_{2}|^{p-2}u_{2} + \beta_{23}|u_{3}|^{p}|u_{3}|^{p-2}u_{3} + \beta_{3}|u_{3}|^{2p-2}u_{1} + \beta_{13}|u_{1}|^{p}|u_{3}|^{p-2}u_{3} + \beta_{23}|u_{2}|^{p}|u_{3}|^{p-2}u_{3} + \beta_{23}|u_{3}|^{p}|u_{3}|^{p-2}u_{3} + \beta_{23}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p-2}u_{3} + \beta_{23}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p}|u_{3}|^{p$$

We have now three explicit solutions of (6): $\mathbf{u}_1 = (U_1, 0, 0), \mathbf{u}_2 = (0, U_2, 0), \mathbf{u}_3 = (0, 0, U_3)$ with U_j solution of (5). Moreover, there could be solutions $\mathbf{u} = (u_1, u_2, u_3)$ having one component equal to 0. Indeed, if $u_k \equiv 0$, the pair $(u_i, u_j), i, j \neq k$, solves (1) with $\beta = \beta_{ij}$. Then, for any (u_i, u_j) solving (1), the function \mathbf{u} with the remaining component equal to 0 solves (6). We denote by \mathbf{u}_{ij} these specific solutions. As in Proposition 2.3, we have:

(1) If
$$p = 2$$
, then

(i) the semi-trivial solutions \mathbf{u}_i , i = 1, 2, 3, are strict local minima of $\Phi|_{\mathcal{M}}$ provided

(7)
$$\beta_{ij} < \gamma_{ij} \qquad \forall \ i, j = 1, 2, 3, \ i \neq j.$$

(*ii*) the semi-trivial solutions
$$\mathbf{u}_i$$
, $i = 1, 2, 3$, are saddle points of $\Phi|_{\mathcal{M}}$ provided

(8)
$$\forall i = 1, 2, 3, \exists j \neq i \text{ such that } \beta_{ij} > \gamma_{ij}.$$

(2) If p > 2 the semi-trivial solutions \mathbf{u}_i , i = 1, 2, 3, are strict local minima of $\Phi|_{\mathcal{M}}$ for all $\beta_{ij} \in \mathbb{R}$, i, j = 1, 2, 3, $i \neq j$.

Therefore, as in Proposition 3.1, we deduce that

(1) If p = 2,

(i) and (7) holds, the functional Φ has a MP critical point \mathbf{u}^* on \mathcal{M} satisfying

(9)
$$\Phi(\mathbf{u}^*) > \max_{i=1,2,3} \Phi(\mathbf{u}_i).$$

(*ii*) and (8) holds, then Φ has a global minimum $\tilde{\mathbf{u}}$ on \mathcal{M} such that

(10)
$$\Phi(\widetilde{\mathbf{u}}) < \min_{i=1,2,3} \Phi(\mathbf{u}_i).$$

(2) If p > 2, for any $\beta \in \mathbb{R}$ the functional Φ has a MP critical point \mathbf{u}^* on \mathcal{M} such that

(11)
$$\Phi(\mathbf{u}^*) > \max_{i=1,2,3} \Phi(\mathbf{u}_i)$$

As for system (1), one can show that $\mathbf{u}^* \ge 0$, $\widetilde{\mathbf{u}} \ge 0$. Nevertheless, although (10) (resp. (9), (11)) implies that $\widetilde{\mathbf{u}} \ne \mathbf{u}_i$, i = 1, 2, 3, (resp. $\mathbf{u}^* \ne \mathbf{u}_i$) it does not implies that $\widetilde{\mathbf{u}}$ is not equal to some \mathbf{u}_{ij} (resp. it does not implies $\mathbf{u}^* \ne \mathbf{u}_{ij}$, for some pair i, j). Summarizing,

Theorem 4.1. If p = 2 and (8) holds, system (6) has a nonegative radial ground state $\widetilde{\mathbf{u}}$.

Theorem 4.2. The following holds:

- (i) If p = 2 and (7) holds, the system (6) has a radial bound state \mathbf{u}^* such that $\mathbf{u}^* \neq \mathbf{u}_i$, i = 1, 2, 3. Moreover, if all $\beta_{ij} > 0$, then $\mathbf{u}^* \ge 0$.
- (ii) If p > 2, system (6) has a radial bound state \mathbf{u}^* such that $\mathbf{u}^* \neq \mathbf{u}_i$, i = 1, 2, 3 for all $\beta_{ij} \in \mathbb{R}$, i, j = 1, 2, 3, $i \neq j$. Moreover, if all $\beta_{ij} > 0$ then $\mathbf{u}^* \ge 0$.

We can still extend Theorems 3.2 and 3.3 to system (2) with $m \geq 3$ equations and $\beta_{ij} = \beta_{ji}$. A proof similar to [25, Theorem 2.1] allow us to extend Theorem 3.2 to prove existence of positive ground states for any $p \geq 2$, since this technique does not rely on the character of the semi-trivial solutions as a critical points (in contrast with Theorem 3.3, which strongly relies on which type of critical points the semi-trivial solutions are for $\Phi|_{\mathcal{M}}$, an inherited feature from Proposition 2.3). For $\lambda > 0$ let us define

$$\mathcal{E}(\mathbf{u}) = \frac{\|\mathbf{u}\|_{\mathbb{E}^m}^2}{\left(\sum_{j=1}^m \mu_j \int_{\mathbb{R}^N} |u_j|^{2p} dx + \sum_{\substack{i,j=1\\i \neq j}}^m \beta_{ij} \int_{\mathbb{R}^N} |u_i|^p |u_j|^p dx\right)^{\frac{1}{p}}} \quad \text{and} \quad \Theta_{\lambda} = \frac{\int_{\mathbb{R}^N} |(-\Delta)^{\frac{s}{2}} U|^2 + U^2 dx}{\int_{\mathbb{R}^N} |(-\Delta)^{\frac{s}{2}} U|^2 + \lambda U^2 dx}$$

Theorem 4.3. Assume that, for some $\lambda > 0$,

$$(\mathcal{H}) \qquad \sum_{j=1}^{m} \mu_{j} \Theta_{\frac{\lambda_{j}}{\lambda}}^{p} + \sum_{\substack{i,j=1\\i\neq j}}^{m} \beta_{ij} \left(\Theta_{\frac{\lambda_{i}}{\lambda}} \Theta_{\frac{\lambda_{j}}{\lambda}}\right)^{\frac{p}{2}} > m^{2} \left\{ \max_{1 \leq j \leq m} \mu_{j} \left(\frac{\lambda}{\lambda_{j}}\right)^{p-\frac{N}{2s}(p-1)} + \max_{\substack{1 \leq i,j \leq m\\i\neq j}} \beta_{ij} \left(\frac{\lambda^{2}}{\lambda_{i}\lambda_{j}}\right)^{\frac{p}{2}-\frac{N}{2s}\left(\frac{p}{2}-\frac{1}{2}\right)} \right\},$$

then, system (2) has a positive radial ground state $\widetilde{\mathbf{u}}$. Moreover, the ground state $\widetilde{\mathbf{u}}$ is given, up to a Lagrange multiplier, by $\inf_{\mathbf{u}\in\mathbb{R}^m\setminus\{\mathbf{0}\}} \mathcal{E}(\mathbf{u})$.

We prove the existence of a *positive bound state* of system (2) for β_{ij} small enough.

Theorem 4.4. If $\beta_{jk} = \varepsilon b_{ij}$ for i, j = 1, 2, ..., m, $i \neq j$ and $|\varepsilon|$ small enough, then system (6) has a radial bound state \mathbf{u}_{ε} such that $\mathbf{u}_{\varepsilon} \to \mathbf{z} := (U_1, U_2, ..., U_m)$ as $\varepsilon \to 0$. Moreover, if $\beta_{ij} = \varepsilon b_{ij} > 0$ then $\mathbf{u}_{\varepsilon} > \mathbf{0}$.

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