# Stabbing convex subdivisions with $k$-flats 

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#### Abstract

We prove that for every convex subdivision of $\mathbb{R}^{d}$ into $n$ cells there exists a $k$-flat stabbing $\Omega\left((\log n / \log \log n)^{1 /(d-k)}\right)$ of them. As a corollary we deduce that every $d$-polytope with $n$ vertices has a $k$-shadow with $\Omega\left((\log n / \log \log n)^{1 /(d-k)}\right)$ vertices.


Keywords: Convex subdivision, stabbing number, Moser's shadow problem

## 1 Introduction

In a famous list of open problems in combinatorial geometry from 1966 (see [2] and [4]), Moser asked for the largest $\mathfrak{s}(n)$ such that every 3 -polytope with $n$ vertices has a 2 -dimensional projection with at least $\mathfrak{s}(n)$ vertices. The solution to this problem, popularly known as Moser's shadow problem, was implicit in the work of Chazelle, Edelsbrunner and Guibas in 1989 [1] but went unnoticed until recently [3].

[^0]The results of [1] imply that $\mathfrak{s}(n)=\theta(\log n / \log \log n)$. The lower bound was derived from a related result concerning stabbing numbers of convex subdivisions of the plane by lines, that Tóth generalized to stabbing numbers of convex subdivisions of $\mathbb{R}^{d}$ by lines [5]. He showed that for each convex subdivision of $\mathbb{R}^{d}$ into $n$ regions there is a line stabbing $\Omega\left((\log n / \log \log n)^{1 /(d-1)}\right)$ cells. In the polytopal set-up, this implies that every $d$-polytope with $n$ vertices has a 2 -dimensional shadow with at least $\Omega\left((\log n / \log \log n)^{1 /(d-2)}\right)$ vertices, and the case $d=2$ for subdivisions and $d=3$ for convex polytopes is the aforementioned work [1].

In this note, we consider the same questions with lines and 2-dimensional shadows replaced by $k$-flats and $k$-shadows (open problems formulated in [5] and [3], respectively). In particular, we prove that for every convex subdivision of $\mathbb{R}^{d}$ into $n$ cells there exists a $k$-flat stabbing $\Omega\left((\log n / \log \log n)^{1 /(d-k)}\right)$ of its cells, and that every $d$-polytope with $n$ vertices has a $k$-shadow with $\Omega\left((\log n / \log \log n)^{1 /(d-k)}\right)$ vertices.

## 2 Stabbing convex subdivisions with $k$-flats

A convex subdivision of $\mathbb{R}^{d}$ is a finite collection of closed convex $d$-dimensional sets, the cells, that cover $\mathbb{R}^{d}$ and whose interiors are pairwise disjoint. We say that a $k$-flat, an affine subspace of dimension $k$, stabs a cell if it intersects its interior. Following Chazelle-Edelsbrunner-Guibas [1] and Tóth [5] we prove the following:
Theorem 2.1 There exists a constant $c_{d}>0$ such that for any subdivision of $\mathbb{R}^{d}$ into $n$ convex cells, and $0<k<d$, there exists a $k$-flat stabbing at least $c_{d}\left(\frac{\log n}{\log \log n}\right)^{\frac{1}{d-k}}$ cells of the subdivision.

It follows easily from the following lemma.
Lemma 2.2 Let $\mathcal{S}$ be convex subdivision of $\mathbb{R}^{d}$ into $n>\ell^{(2 \ell)^{d-k}}$ cells, where $0<k<d$ and $\ell \geq 2$. Then for any generic direction $v$, either there is a line parallel to $v$ stabbing $\ell$ cells, or there is hyperplane transversal to $v$ stabbing at least $\ell^{(2 \ell)^{d-k-1}}$ cells.

Proof. Set $\lambda=\ell^{(2 \ell)^{d-k-1}}$ and assume that there is no hyperplane transversal to $v$ stabbing at least $\lambda$ cells. In $\ell$ steps, we will construct a collection of cells $C_{0}, \ldots, C_{\ell}$ that are all simultaneously stabbed by the same line in direction $v$.

First consider the infinite cells $A_{0}$ and $B_{0}$ such that $t v \in A_{0}$ and $-t v \in B_{0}$ for all $t>0$ sufficiently large. We set $Z_{0}:=\mathbb{R}^{d} \backslash\left(A_{0} \cup B_{0}\right)$ and $\mathcal{S}_{0}:=$ $\mathcal{S} \backslash\left\{A_{0}, B_{0}\right\}$. Note that all the points $p \in Z_{0}$ are between $A_{0}$ and $B_{0}$ in
the direction $v$; that is, the intersection of any line parallel to $v$ with $Z_{0}$ is a segment starting at $A_{0}$ and finishing at $B_{0}$ (and thus if the line intersects the interior of $Z_{0}$ it will stab both $A_{0}$ and $B_{0}$ ). We call such a set a $v$-cylinder, and $A_{0}$ and $B_{0}$ its bases. Note also that $\mathcal{S}_{0}=\left\{C \in \mathcal{S}: Z_{0} \cap C \neq \emptyset\right\}$.

In the following we consider only hyperplanes that are transversal to the direction $v$. For a given such hyperplane $H$, we will consider the cells that intersect it in a $(d-1)$-face. We will say that such a cell intersects $H$ above or below if it intersects $H^{+}$or $H^{-}$, respectively, where $H^{ \pm}=\{x \pm t v: x \in$ $H, t>0\}$. Note that cells that intersect $H$ and are not tangent to $H$ will intersect both above and below.

To find the cells $C_{i}$, we will construct a nested family of $v$-cylinders $Z_{\ell} \subset$ $Z_{\ell-1} \subset \cdots \subset Z_{0}$. The bases of $Z_{i}$ will be $A_{i}$ and $B_{i}$, one of which will be chosen to be $C_{i}$. To this end, assume that at the $i$-th step we have chosen $A_{i}$ and $B_{i}$, and a $v$-cylinder $Z_{i}$ that has them as bases. We put $\mathcal{S}_{i}:=\left\{C \in \mathcal{S}: Z_{i} \cap C \neq \emptyset\right\}$. Then we choose a hyperplane $H_{i}$ that weakly separates $A_{i}$ from $B_{i}$ (which exists since $A_{i}$ and $B_{i}$ are convex and with disjoint interiors).

Let $\mathcal{T}_{i}^{+}$and $\mathcal{T}_{i}^{-}$be the cells of $\mathcal{S}_{i}$ that intersect $H_{i}$ above and below, respectively. Note that by perturbing $H_{i}$ to $H_{i} \pm \epsilon v$ with $\epsilon$ arbitrarily small, the hyperplane stabs all the cells in $\mathcal{T}_{i}^{ \pm}$, and hence by assumption $\left|\mathcal{T}_{i}^{ \pm}\right|<\lambda$. Now, we subdivide $H_{i}^{+} \cap Z_{i}$ into $\left|\mathcal{T}_{i}^{+}\right| v$-monotone regions as follows. For each cell $C \in \mathcal{T}_{i}^{+}$, we consider the set of points $p \in H_{i}^{+} \cap Z_{i}$ such that the last region intersected by a ray cast from $p$ in direction $-v$ before hitting $H_{i}$ is $C$; that is, that the ray pierces $C \cap H_{i}$. If $H_{i}$ is generic, these are just the intersections of $H_{i}^{+} \cap Z_{i}$ with the cylinders in direction $v$ spanned by each of the regions of $H_{i} \cap \mathcal{S}_{i}$. But since the subdivision was not required to be face-to-face and $H_{i}$ might be tangent to a cell of $\mathcal{S}_{i}, H_{i} \cap \mathcal{S}_{i}$ is not necessarily well defined, and we have to distinguish the induced subdivision from above and from below.

The regions constructed this way cover $H_{i}^{+} \cap Z_{i}$. Subtracting $C$ from its associated region we obtain a $v$-cylinder $Z_{C}^{+}$between $C$ and $A_{i}$. (Some of these cylinders might be empty, if $A_{i}$ intersects some cell in $\mathcal{T}_{i}^{+}$.) For each $C \in \mathcal{T}_{i}^{-}$, we construct analogously a $v$-cylinder $Z_{C}^{-} \subset H_{i}^{-} \cap Z_{i}$ with bases $C$ and $B_{i}$.

Note that the union of all these $v$-cylinders covers all $Z_{i} \backslash\left(\mathcal{T}_{i}^{+} \cup \mathcal{T}_{i}^{-}\right)$ (and maybe more, because the cells in $\mathcal{T}_{i}^{+} \cup \mathcal{T}_{i}^{-}$might intersect the cylinders defined by other cells). Hence, by the pigeonhole principle, there must be one of them, that we define to be $Z_{i+1}$, that intersects at least

$$
\frac{\left|\mathcal{S}_{i}\right|-\left|\mathcal{T}_{i}^{+} \cup \mathcal{T}_{i}^{-}\right|}{\left|\mathcal{T}_{i}^{+}\right|+\left|\mathcal{T}_{i}^{-}\right|}
$$

cells of $\mathcal{S}_{i}$. If it belongs to $H_{i}^{+}$we define $C_{i}:=B_{i}, A_{i+1}:=A_{i}$ and $B_{i+1}$ to be the corresponding cell of $\mathcal{T}_{i}^{+} ;$and if the cylinder belongs to $H_{i}^{-}$we set $C_{i}:=A_{i}, B_{i+1}:=B_{i}$, and $A_{i+1}$ to be the corresponding cell of $\mathcal{T}_{i}^{-}$. We put $\mathcal{S}_{i+1}:=\left\{C \in \mathcal{S}: Z_{i+1} \cap C \neq \emptyset\right\}$ and continue inductively until this set is empty.

Now, by induction on $i$ we see that $\left|\mathcal{S}_{i}\right|>\frac{n}{(2 \lambda)^{i}}-2$ for $0 \leq i<\ell$. Indeed, $\left|\mathcal{S}_{0}\right|=n-2$ by construction and for $i>0$ we have

$$
\left|\mathcal{S}_{i}\right|>\frac{\left|\mathcal{S}_{i-1}\right|-2 \lambda}{2 \lambda}>\frac{\frac{n}{(2 \lambda)^{i-1}}-2}{2 \lambda}-1>\frac{n}{(2 \lambda)^{i}}-2 .
$$

In particular,

$$
\left|\mathcal{S}_{i}\right|>\frac{\ell^{(2 \ell)^{d-k}}}{2^{i} \ell^{i(2 \ell)^{d-k-1}}}-2=\frac{\ell^{(2 \ell-i)(2 \ell)^{d-k-1}}}{2^{i}}-2 ;
$$

which is larger than 0 whenever $i<\ell$. Hence, the process does not finish in less than $\ell$ steps.

Observe that our construction ensures that $\left\{A_{i}, B_{i}\right\} \neq\left\{A_{i+1}, B_{i+1}\right\}$, and that the chosen cells $C_{i} \in\left\{A_{i}, B_{i}\right\} \backslash\left\{A_{i+1}, B_{i+1}\right\}$ are all distinct. Since the cylinders are nested, $Z_{i+1} \subset Z_{i}$, any line in direction $v$ through the interior the last non-empty cylinder stabs each of the cells $C_{i}$.

Proof of Theorem 2.1 We prove, by induction on $d$, that for any subdivision of $\mathbb{R}^{d}$ into $n>\ell^{(2 \ell)^{d-k}}$ convex cells, there exists a $k$-flat intersecting at least $\ell$ cells. For $d=r$ there is nothing to prove. If $d>r$, assume that for any convex subdivision of $\mathbb{R}^{d-1}$ into $\ell^{(2 \ell)^{d-1-r}}$ cells there exists a $k$-flat intersecting at least $\ell$-cells.

Applying the lemma to the original subdivision we get an alternative: if the subdivision contains a line stabbing $\ell$ elements then we are done as any $k$-flat containing the line intersects at least this number of cells. Otherwise there exists a hyperplane $H$ intersecting $\ell^{(2 \ell)^{d-r-1}}$ cells. By the induction hypothesis on the subdivision induced on $H$, there is a $k$-flat contained in $H$ that intersects at least $\ell$ cells.

## 3 Moser's shadow problem in high dimensions

A $k$-shadow of a convex polytope $P$ is a $k$-dimensional polytope that is the image of $P$ under a linear map.

Theorem 3.1 There exists a constant $c_{d}^{\prime}>0$ such that for $1<k<d$, every $d$-polytope with $n$ vertices has a $k$-shadow with at least $c_{d}^{\prime}\left(\frac{\log n}{\log \log n}\right)^{\frac{1}{d-k}}$ vertices.

Proof. Let $P$ be a $d$-polytope with $n$ vertices, and $\pi$ the orthogonal projection of $\mathbb{R}^{d}$ onto a $k$-dimensional linear subspace $L$. Then, if $\mathcal{N}(P)$ is the normal fan of $P$, the normal fan of $\pi(P)$ is isomorphic to $\mathcal{N}(P) \cap L$ (see [6, Lem. 7.11]).

Now consider the spherical subdivision of $\mathbb{S}^{d-1}$ induced by $\mathcal{N}(P)$. It has $n$ ( $d-1$ )-dimensional regions, one for each vertex, and after a suitable rotation we might assume that the lower hemisphere intersects at least $\frac{n}{2}$ of them. Central projection from the origin maps this subdivision of the lower hemisphere onto a convex subdivision of $\mathbb{R}^{d-1}$ into at least $\frac{n}{2}$ cells. By Theorem 2.1, there is a ( $k-1$ )-flat that intersects at least

$$
c_{d}\left(\frac{\log \frac{n}{2}}{\log \log \frac{n}{2}}\right)^{\frac{1}{(d-1)-(k-1)}} \geq c_{d}^{\prime}\left(\frac{\log n}{\log \log n}\right)^{\frac{1}{d-k}}
$$

cells of this subdivision. The pre-image of this ( $k-1$ )-flat spans a $k$-dimensional linear subspace $L$ intersecting at least $c_{d}^{\prime}\left(\frac{\log n}{\log \log n}\right)^{\frac{1}{d-k}}$ cells of $\mathcal{N}(P)$. Therefore, the orthogonal projection of $P$ onto $L$ is a $k$-shadow with at least this many vertices.

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