



UNIVERSIDAD DE BURGOS
MATHEMATICAL PHYSICS GROUP

Lorentzian Poisson homogeneous spaces

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Outline

- 1 Motivation: Noncommutative spacetimes
- 2 Poisson-Lie groups and Poisson homogeneous spaces
- 3 $(2+1)$ Poincaré PHS from Drinfel'd doubles
- 4 A Lorentzian PHS in $(3+1)$ dimensions
- 5 Open problems

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'Noncommutative' space-times can be used to describe relevant physical phenomena at the Planck scale (very high energy/curvature).

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$$[\hat{x}^i, \hat{x}^j]_{\lambda_P} \neq 0 \quad \implies \quad \Delta \hat{x}^i \cdot \Delta \hat{x}^j \geq \frac{1}{2} | \langle [\hat{x}^i, \hat{x}^j]_{\lambda_P} \rangle | > 0$$

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- This 'quantum' spacetime algebra should be a 'Planck scale' (λ_P) **deformation** of the 'classical' commutative spacetime:

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Many different physical contexts since Snyder (1947): nc field theory, string spacetimes, (2+1) quantum gravity, DSR and modified dispersion relations... Also different mathematical approaches to noncommutative geometry.

[see R. J. Szabo, Physics Reports 378, 207-299 (2003)].

There are many possibilities in order to introduce noncommutative algebras of spacetime 'coordinates'.

A mathematically consistent one is provided by **quantum groups**:

Deformations G_q of the Hopf algebra of functions on Lie groups or, equivalently, Hopf algebra deformations $U_q(\mathfrak{g})$ of the universal enveloping algebra of $\mathfrak{g} = \text{Lie}(G)$ [Drinfel'd, Manin, Woronowicz].

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- 'Quantum spacetimes' can be constructed as noncommutative algebras that are **covariant under quantum group (co)actions**.
- The 'quantum' deformation parameter would depend on some Planck scale parameter: $q = q(\lambda_P)$ such that $\lim_{\lambda_P \rightarrow 0} q = 1$.
- In particular, **quantum (Anti)-de Sitter and Minkowski spacetimes** can be constructed as **quantum homogeneous spaces** of the corresponding quantum kinematical groups $SO_q(4, 1)$, $SO_q(3, 2)$ and $ISO_q(3, 1)$.

Maximally symmetric spacetimes (AdS, dS, Minkowski) are **classical homogeneous spaces** $M = G/H$, where H is the Lorentz isotropy subgroup $SO(3, 1)$ and G is, respectively, $SO(3, 2)$, $SO(4, 1)$ and $ISO(3, 1)$.

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- Since H is a subgroup of G , the deformation H_q is fixed by the deformation G_q .
- Imposing that **H_q is a quantum subgroup** (i.e., a Hopf subalgebra of G_q) turns out to be **too restrictive**.
[Dijkhuizen and Koornwinder, 1994]

Why Poisson homogeneous spaces

Main results: [Drinfel'd]

Quantum groups G_q are **quantizations of Poisson-Lie groups** (G, Π) and **quantum homogeneous spaces** M_q are **quantizations of Poisson homogeneous spaces** (M, π) .

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- Poisson-Lie groups (G, Π) are in one-to-one correspondence with **Lie bialgebra structures** (\mathfrak{g}, δ) .
- Poisson homogeneous spaces (M, π) are in one-to-one correspondence with **with Lagrangian Lie subalgebras ℓ of the Drinfel'd double Lie algebra $D(\mathfrak{g})$** associated to δ .

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- In order to be able to obtain the π bracket through canonical projection from the PL bracket Π , the isotropy subgroup H has to be **coisotropic with respect to δ** :

$$\delta(\mathfrak{h}) \subset \mathfrak{h} \wedge \mathfrak{g}, \quad \mathfrak{h} = \text{Lie}(H).$$

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- A particular case: when H is a **Poisson-Lie subgroup**

$$\delta(\mathfrak{h}) \subset \mathfrak{h} \wedge \mathfrak{h},$$

its quantization would give rise to a quantum subgroup H_q .

As a consequence, for **the same 'classical' $M = G/H$ we have different admissible Poisson (noncommutative) homogeneous structures.**

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- ① We have **as many possible PL structures Π on G as Lie bialgebra structures (g, δ)** , whose dual δ^* is just the linearization of Π :

$$\{x, x\}_{\Pi} = A(x, \xi) \quad \{x, \xi\}_{\Pi} = B(x, \xi) \quad \{\xi, \xi\}_{\Pi} = C(x, \xi).$$

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The **coisotropy condition** ensures that π **can be obtained as the projection of Π onto the PHS coordinates**:

$$\{x, x\}_{\pi} = \{x, x\}_{\Pi} = A(x, 0) = F(x).$$

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Construct (A)dS and Minkowskian PHS and analyse their properties as a preliminary step for the construction of their associated QHS.

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- In **(2+1) dimensions** PL structures are fully described through the classifications of the corresponding (coboundary) Lie bialgebras:
 - Poincaré Lie algebra [Stachura, 1998]
 - dS and AdS Lie algebras [Zakrzewski 1994, Borowiec, Lukierski and Tolstoy, 2016]

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These classifications are **not written in a suitable kinematical basis** $\{J, K, P\}$ giving rise to the PHS with usual x^μ Minkowski coordinates.

In particular:

Some examples of Lorentzian PHS:

- In $(2+1)$ dimensions, **Minkowski PHS coming from all possible Drinfel'd double structures of the $(2+1)$ Poincaré Lie algebra** are constructed. The DD (A)dS Poisson-Lie groups are known. ¹
- **A PHS for the $(3+1)$ -dimensional AdS group** with respect to the so-called κ -Poisson-Lie structure is explicitly given.

Its **Minkowskian limit** can be obtained when the cosmological constant vanishes.

¹A.B., F.J. Herranz, C. Meusburger, *Class. Quantum Grav.* 30 (2013), 155012

2. POISSON-LIE GROUPS AND POISSON HOMOGENEOUS SPACES

A **Poisson-Lie group** (G, Π) is a Lie group G that is also a Poisson manifold such that the **multiplication map for G is a Poisson map**.

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Theorem [Drinfel'd]. Let G be a Lie group with Lie algebra \mathfrak{g} :

- If (G, Π) is a Poisson-Lie group, then \mathfrak{g} has a natural Lie bialgebra structure (\mathfrak{g}, δ) , called the tangent Lie bialgebra of G .
- Conversely, if G is connected and simply connected, every Lie bialgebra structure (\mathfrak{g}, δ) is the tangent Lie bialgebra of a unique Poisson structure on G which makes G into a Poisson-Lie group.

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The **cocommutator map** $\delta : \mathfrak{g} \rightarrow \mathfrak{g} \otimes \mathfrak{g}$ is such that:

- i) δ is a **1-cocycle**, i.e.,

$$\delta([X, Y]) = [\delta(X), 1 \otimes Y + Y \otimes 1] + [1 \otimes X + X \otimes 1, \delta(Y)], \quad \forall X, Y \in \mathfrak{g}.$$
- ii) The **dual map** $\delta^* : \mathfrak{g}^* \otimes \mathfrak{g}^* \rightarrow \mathfrak{g}^*$ is a **Lie bracket** on \mathfrak{g}^* .

- In some cases the 1-cocycle δ is a **coboundary**

$$\delta(X) = [1 \otimes X + X \otimes 1, r] \quad X \in \mathfrak{g}$$

where r is a skewsymmetric element of $\mathfrak{g} \otimes \mathfrak{g}$ (the **r -matrix**)

$$r = r^{ab} X_a \wedge X_b$$

which has to be a solution of the **modified classical Yang–Baxter equation** (mCYBE)

$$[X \otimes 1 \otimes 1 + 1 \otimes X \otimes 1 + 1 \otimes 1 \otimes X, [[r, r]]] = 0 \quad X \in \mathfrak{g}.$$

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- For a coboundary Poisson-Lie group G , the Poisson structure Π on G is given by the so-called **Sklyanin bracket**

$$\{f, g\} = r^{ij} \left(\nabla_i^L f \nabla_j^L g - \nabla_i^R f \nabla_j^R g \right), \quad f, g \in \mathcal{C}^\infty(G)$$

where ∇_i^L, ∇_i^R are left- and right-invariant vector fields on G .

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The **Drinfel'd double Lie algebra** $D(\mathfrak{g})$ associated to the Lie bialgebra (\mathfrak{g}, δ) is the Lie algebra structure on the vector space $\mathfrak{g} + \mathfrak{g}^*$ given by

$$[X_i, X_j] = C_{ij}^k X_k, \quad [x^i, x^j] = f_k^{ij} x^k, \quad [x^i, X_j] = C_{jk}^i x^k - f_j^{ik} X_k,$$

where $\{X_1, \dots, X_n\}$ and $\{x^1, \dots, x^n\}$ are dual basis for \mathfrak{g} and \mathfrak{g}^* , under the canonical **pairing**

$$\langle X_i, x^j \rangle = \delta_i^j.$$

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where $\{X_1, \dots, X_n\}$ and $\{x^1, \dots, x^n\}$ are dual basis for \mathfrak{g} and \mathfrak{g}^* , under the canonical pairing

$$\langle X_i, x^j \rangle = \delta_i^j.$$

$D(\mathfrak{g})$ has a **canonical quasi-triangular Lie bialgebra structure** given by

$$r = \sum_i x^i \otimes X_i,$$

since r is always a solution of the CYBE $[[r, r]] = 0$.

Let (G, Π) be a PL group. A **Poisson homogeneous space** is a Poisson manifold (M, π) with a **transitive group action** $\triangleright : G \times M \rightarrow M$ that is a **Poisson map** with respect to the Poisson structure π on M and the product $\Pi \times \pi$ of the Poisson structures on G and M .

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Theorem [Drinfel'd]

Let G be a Poisson-Lie group and let H be a connected subgroup of G . Poisson homogeneous spaces on $M = G/H$ are in **one-to one correspondence with Lagrangian Lie subalgebras ℓ of the double Lie algebra $D(\mathfrak{g})$** such that $\ell \cap \mathfrak{g} = \mathfrak{h}$.

The Lagrangian Lie subalgebra ℓ of the double Lie algebra $D(\mathfrak{g})$ fulfills:

- Maximality: $\dim \ell = \dim \mathfrak{g} \equiv N$.
- Isotropy: $\langle \ell, \ell \rangle = 0$.
- The condition $\ell \cap \mathfrak{g} = \mathfrak{h}$.

3. POINCARÉ PHS FROM DRINFEL'D DOUBLES IN (2+1)

The **(2+1) Poincaré Lie algebra**:

$$\begin{array}{lll}
 [J, K_1] = K_2, & [J, K_2] = -K_1, & [K_1, K_2] = -J, \\
 [J, P_0] = 0, & [J, P_1] = P_2, & [J, P_2] = -P_1, \\
 [K_1, P_0] = P_1, & [K_1, P_1] = P_0, & [K_1, P_2] = 0, \\
 [K_2, P_0] = P_2, & [K_2, P_1] = 0, & [K_2, P_2] = P_0, \\
 [P_0, P_1] = 0, & [P_0, P_2] = 0, & [P_1, P_2] = 0,
 \end{array}$$

Two quadratic Casimirs:

$$C_1 = P_0^2 - P_1^2 - P_2^2,$$

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(2+1) gravity can be described as a Chern-Simons gauge theory whose symplectic structure can be defined in terms of PL structures [Fock and Rosly 1992, Alekseev and Malkin 1995], and the most natural PL structures are those coming from classical Drinfel'd doubles [Meusburger and Schroers, 2009].

$$[Y_i, Y_j] = C_{ij}^k Y_k \quad [y^i, y^j] = f_k^{ij} y^k \quad [y^i, Y_j] = C_{jk}^i y^k - f_j^{ik} Y_k$$

Table 1: The eighth non-equivalent DD Lie algebras which are isomorphic to the (2+1) Poincaré algebra. The parameter ω can be rescaled to any non-zero real number of the same sign, while λ is an essential parameter. In Case 5 they must obey $\omega\lambda > 0$. In Case 6 we have $\omega > 0$.

	Case 0	Case 1	Case 2	Case 3	Case 4	Case 5	Case 6	Case 7
$[Y_0, Y_1]$	$2Y_1$	Y_1	Y_1	Y_1	$-Y_2$	Y_1	Y_1	$-Y_2$
$[Y_0, Y_2]$	$-2Y_2$	Y_2	Y_2	$Y_1 + Y_2$	Y_1	$Y_1 + Y_2$	Y_2	Y_1
$[Y_1, Y_2]$	Y_0	0	0	0	0	0	0	0
$[y^0, y^1]$	0	y^0	0	λy^2	0	λy^2	0	0
$[y^0, y^2]$	0	y^1	y^1	0	$-y^0$	0	y^1	$-y^0$
$[y^1, y^2]$	0	y^2	0	0	$\lambda y^0 - y^1$	$2\omega y^0$	$2\omega y^0$	$-y^1$
$[y^0, Y_0]$	0	$-Y_1$	0	0	$-Y_2$	0	0	Y_2
$[y^0, Y_1]$	y^2	$-Y_2$	$-Y_2$	0	$\lambda Y_2 - y^2$	0	$-Y_2$	0
$[y^0, Y_2]$	$-y^1$	0	0	$-\lambda y^1$	$Y_0 - \lambda Y_1 + y^1$	$-\lambda Y_1$	0	0
$[y^1, Y_0]$	$2y^1$	$Y_0 + y^1$	y^1	$y^1 + y^2$	0	$-2\omega Y_2 + y^1 + y^2$	$-2\omega Y_2 + y^1$	y^2
$[y^1, Y_1]$	$-2y^0$	$-y^0$	$-y^0$	$-y^0$	$-Y_2$	$-y^0$	$-y^0$	Y_2
$[y^1, Y_2]$	0	$-Y_2$	0	$\lambda Y_0 - y^0$	$Y_1 - y^0$	$\lambda Y_0 - y^0$	0	$-y^0$
$[y^2, Y_0]$	$-2y^2$	y^2	y^2	y^2	0	$2\omega Y_1 + y^2$	$2\omega Y_1 + y^2$	$-Y_0 - y^1$
$[y^2, Y_1]$	0	Y_0	Y_0	0	y^0	0	Y_0	$-Y_1 + y^0$
$[y^2, Y_2]$	$2y^0$	$Y_1 - y^0$	$-y^0$	$-y^0$	0	$-y^0$	$-y^0$	0

- A **generic element of the $P(2+1)$ group** is constructed as

$$G = \exp(x^0 \rho(P_0)) \exp(x^1 \rho(P_1)) \exp(x^2 \rho(P_2)) \exp(\xi^1 \rho(K_1)) \exp(\xi^2 \rho(K_2)) \exp(\theta \rho(J)).$$

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- $\{x^0, x^1, x^2\}$ are **local coordinates on the homogeneous Minkowski spacetime** defined as $M = G/H$ with $H = \{J, K_1, K_2\}$.

- A **generic element of the $P(2+1)$ group** is constructed as

$$G = \exp(x^0 \rho(P_0)) \exp(x^1 \rho(P_1)) \exp(x^2 \rho(P_2)) \exp(\xi^1 \rho(K_1)) \exp(\xi^2 \rho(K_2)) \exp(\theta \rho(J)).$$

- $\{x^0, x^1, x^2\}$ are **local coordinates on the homogeneous Minkowski spacetime** defined as $M = G/H$ with $H = \{J, K_1, K_2\}$.
- Left and right invariant vector fields on $P(2+1)$ are:

$$\nabla_J^L = \partial_\theta,$$

$$\nabla_{K_1}^L = \frac{\cos \theta}{\cosh \xi^2} (\partial_{\xi^1} + \sinh \xi^2 \partial_\theta) + \sin \theta \partial_{\xi^2},$$

$$\nabla_{K_2}^L = -\frac{\sin \theta}{\cosh \xi^2} (\partial_{\xi^1} + \sinh \xi^2 \partial_\theta) + \cos \theta \partial_{\xi^2},$$

$$\nabla_{P_0}^L = \cosh \xi^2 (\cosh \xi^1 \partial_{x^0} + \sinh \xi^1 \partial_{x^1}) + \sinh \xi^2 \partial_{x^2},$$

$$\nabla_{P_1}^L = \cos \theta (\sinh \xi^1 \partial_{x^0} + \cosh \xi^1 \partial_{x^1}) + \sin \theta (\sinh \xi^2 (\cosh \xi^1 \partial_{x^0} + \sinh \xi^1 \partial_{x^1}) + \cosh \xi^2 \partial_{x^2}),$$

$$\nabla_{P_2}^L = -\sin \theta (\sinh \xi^1 \partial_{x^0} + \cosh \xi^1 \partial_{x^1}) + \cos \theta (\sinh \xi^2 (\cosh \xi^1 \partial_{x^0} + \sinh \xi^1 \partial_{x^1}) + \cosh \xi^2 \partial_{x^2}),$$

$$\nabla_J^R = -x^2 \partial_{x^1} + x^1 \partial_{x^2} + \frac{\cosh \xi^1}{\cosh \xi^2} (\partial_\theta - \sinh \xi^2 \partial_{\xi^1}) + \sinh \xi^1 \partial_{\xi^2},$$

$$\nabla_{K_1}^R = x^1 \partial_{x^0} + x^0 \partial_{x^1} + \partial_{\xi^1},$$

$$\nabla_{K_2}^R = x^2 \partial_{x^0} + x^0 \partial_{x^2} + \frac{\sinh \xi^1}{\cosh \xi^2} (-\sinh \xi^2 \partial_{\xi^1} + \partial_\theta) + \cosh \xi^1 \partial_{\xi^2},$$

$$\nabla_{P_0}^R = \partial_{x^0}, \quad \nabla_{P_1}^R = \partial_{x^1}, \quad \nabla_{P_2}^R = \partial_{x^2}.$$

Table 2: The (2+1) Poincaré r -matrices and Poisson subgroup/coisotropy condition for each of the eight DD structures on $\mathfrak{p}(2+1)$ as well as the corresponding class in the Stachura classification.

Case	Classical r -matrix r'_i	$\delta_D(\mathfrak{h})$	Stachura class.
0	$\frac{1}{2}(-P_0 \wedge J - P_1 \wedge K_2 + P_2 \wedge K_1)$	$= 0$	(IV)
1	$K_1 \wedge J + K_1 \wedge K_2 + (-P_0 \wedge J - P_1 \wedge K_2 + P_2 \wedge K_1)$	$\subset \mathfrak{h} \wedge \mathfrak{h}$	(I)
2	$P_2 \wedge J - P_0 \wedge K_2 - P_2 \wedge K_2 + \frac{1}{2}(P_0 \wedge J - P_1 \wedge K_2 + P_2 \wedge K_1)$	$\subset \mathfrak{h} \wedge \mathfrak{g}$	(IIa)
3	$-P_2 \wedge J - P_0 \wedge K_2 - P_2 \wedge K_2 + \frac{1}{2}(-P_0 \wedge J + P_1 \wedge K_2 - P_2 \wedge K_1)$ $+ \frac{1}{\lambda}(P_0 \wedge P_1 + 2(P_0 \wedge P_2 + P_2 \wedge P_1))$	$\not\subset \mathfrak{h} \wedge \mathfrak{g}$	(IIa)
4	$P_2 \wedge J + \frac{1}{2}(P_0 \wedge J - P_1 \wedge K_2 + P_2 \wedge K_1) + \lambda P_0 \wedge P_2$	$\not\subset \mathfrak{h} \wedge \mathfrak{g}$	(IIIb)
5	$P_1 \wedge J + \frac{1}{2}(-P_0 \wedge J + P_1 \wedge K_2 - P_2 \wedge K_1) + \frac{1}{\lambda}P_1 \wedge P_0$	$\not\subset \mathfrak{h} \wedge \mathfrak{g}$	(IIIb)
6	$P_0 \wedge K_2 + \frac{1}{2}(-P_0 \wedge J + P_1 \wedge K_2 + P_2 \wedge K_1)$	$\subset \mathfrak{h} \wedge \mathfrak{g}$	(IIIb)
7	$P_2 \wedge J + \frac{1}{2}(-P_0 \wedge J + P_1 \wedge K_2 - P_2 \wedge K_1)$	$\subset \mathfrak{h} \wedge \mathfrak{g}$	(IIIb)

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3	$-P_2 \wedge J - P_0 \wedge K_2 - P_2 \wedge K_2 + \frac{1}{2}(-P_0 \wedge J + P_1 \wedge K_2 - P_2 \wedge K_1)$ $+ \frac{1}{\lambda}(P_0 \wedge P_1 + 2(P_0 \wedge P_2 + P_2 \wedge P_1))$	$\not\subset \mathfrak{h} \wedge \mathfrak{g}$	(IIa)
4	$P_2 \wedge J + \frac{1}{2}(P_0 \wedge J - P_1 \wedge K_2 + P_2 \wedge K_1) + \lambda P_0 \wedge P_2$	$\not\subset \mathfrak{h} \wedge \mathfrak{g}$	(IIIb)
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Among the eight r -matrices generating the (2+1) PL structures:

- We have **five coisotropic cases** with respect to the Lorentz isotropy subalgebra.
- Cases 0 and 1 are of **Poisson subgroup** type.
- All the r -matrices should be multiplied by a constant (λ_P).

DD Poisson Minkowski spacetimes in (2+1) dimensions

Case 0

$$\{x^0, x^1\} = -x^2, \quad \{x^0, x^2\} = x^1, \quad \{x^1, x^2\} = x^0,$$

Case 1

$$\begin{aligned} \{x^0, x^1\} &= -x^2(x^0 + x^1) + 2x^2, \\ \{x^0, x^2\} &= x^1(x^0 + x^1) - 2x^1, \\ \{x^1, x^2\} &= x^0(x^0 + x^1) - 2x^0, \end{aligned}$$

Case 2

$$\{x^0, x^1\} = 0, \quad \{x^0, x^2\} = -(x^0 - x^2), \quad \{x^1, x^2\} = -(x^0 - x^2),$$

Case 6

$$\{x^0, x^1\} = 0, \quad \{x^0, x^2\} = -x^0 + x^1, \quad \{x^1, x^2\} = 0,$$

Case 7

$$\{x^0, x^1\} = 0, \quad \{x^0, x^2\} = 0, \quad \{x^1, x^2\} = -(x^0 + x^2).$$

Quantization is **non-trivial for Case 2** (quadratic Poisson algebra).

4. A LORENTZIAN PHS IN (3+1) DIMENSIONS

The **(3+1)D AdS_ω Lie algebra** ($\omega = -\Lambda$):

$$\begin{aligned}
 [J_a, J_b] &= \epsilon_{abc} J_c, & [J_a, P_b] &= \epsilon_{abc} P_c, & [J_a, K_b] &= \epsilon_{abc} K_c, \\
 [K_a, P_0] &= P_a, & [K_a, P_b] &= \delta_{ab} P_0, & [K_a, K_b] &= -\epsilon_{abc} J_c, \\
 [P_0, P_a] &= \omega K_a, & [P_a, P_b] &= -\omega \epsilon_{abc} J_c, & [P_0, J_a] &= 0.
 \end{aligned}$$

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Explicitly, **AdS_ω³⁺¹** comprises the three following Lorentzian spacetimes:

- $\omega > 0, \Lambda < 0$: AdS spacetime **AdS³⁺¹** $\equiv \text{SO}(3, 2)/\text{SO}(3, 1)$.
- $\omega < 0, \Lambda > 0$: dS spacetime **dS³⁺¹** $\equiv \text{SO}(4, 1)/\text{SO}(3, 1)$.
- $\omega = \Lambda = 0$: Minkowski spacetime **M³⁺¹** $\equiv \text{ISO}(3, 1)/\text{SO}(3, 1)$.

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- $\omega = \Lambda = 0$: Minkowski spacetime **M³⁺¹** $\equiv \text{ISO}(3, 1)/\text{SO}(3, 1)$.

Casimir operators: the quadratic one

$$\mathcal{C} = P_0^2 - \mathbf{P}^2 + \omega (\mathbf{J}^2 - \mathbf{K}^2)$$

and the quartic one (Pauli-Lubanski)

$$\mathcal{W} = W_0^2 - \mathbf{W}^2 + \omega (\mathbf{J} \cdot \mathbf{K})^2$$

$$W_0 = \mathbf{J} \cdot \mathbf{P} \quad W_a = -J_a P_0 + \epsilon_{abc} K_b P_c$$

The **classical r -matrix for the AdS κ -deformation** is ²

$$r = z \left(K_1 \wedge P_1 + K_2 \wedge P_2 + K_3 \wedge P_3 + \sqrt{\omega} J_1 \wedge J_2 \right), \quad z = 1/\kappa,$$

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$$r = z \left(K_1 \wedge P_1 + K_2 \wedge P_2 + K_3 \wedge P_3 + \sqrt{\omega} J_1 \wedge J_2 \right), \quad z = 1/\kappa,$$

and the **cocommutator map** reads

$$\delta(P_0) = 0, \quad \delta(J_3) = 0,$$

$$\delta(J_1) = z\sqrt{\omega} J_1 \wedge J_3, \quad \delta(J_2) = z\sqrt{\omega} J_2 \wedge J_3,$$

$$\delta(P_1) = z \left(P_1 \wedge P_0 - \omega J_2 \wedge K_3 + \omega J_3 \wedge K_2 + \sqrt{\omega} J_1 \wedge P_3 \right),$$

$$\delta(P_2) = z \left(P_2 \wedge P_0 - \omega J_3 \wedge K_1 + \omega J_1 \wedge K_3 + \sqrt{\omega} J_2 \wedge P_3 \right),$$

$$\delta(P_3) = z \left(P_3 \wedge P_0 - \omega J_1 \wedge K_2 + \omega J_2 \wedge K_1 - \sqrt{\omega} J_1 \wedge P_1 - \sqrt{\omega} J_2 \wedge P_2 \right),$$

$$\delta(K_1) = z \left(K_1 \wedge P_0 + J_2 \wedge P_3 - J_3 \wedge P_2 + \sqrt{\omega} J_1 \wedge K_3 \right),$$

$$\delta(K_2) = z \left(K_2 \wedge P_0 + J_3 \wedge P_1 - J_1 \wedge P_3 + \sqrt{\omega} J_2 \wedge K_3 \right),$$

$$\delta(K_3) = z \left(K_3 \wedge P_0 + J_1 \wedge P_2 - J_2 \wedge P_1 - \sqrt{\omega} J_1 \wedge K_1 - \sqrt{\omega} J_2 \wedge K_2 \right).$$

The **coisotropy condition** holds $\delta(\mathfrak{h}) \subset \mathfrak{h} \wedge \mathfrak{g}$.

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By **computing the Sklyanin bracket** for the r -matrix and by taking the canonical projection onto the spacetime Poisson subalgebra we get the **(3+1) κ -AdS noncommutative spacetime**³

$$\begin{aligned} \{x_0, x_1\} &= -\frac{z \tanh(\sqrt{\omega} x_1) \operatorname{sech}^2(\sqrt{\omega} x_2) \operatorname{sech}^2(\sqrt{\omega} x_3)}{\sqrt{\omega}} & \omega \rightarrow 0 & -z x_1 \\ \{x_0, x_2\} &= -\frac{z \tanh(\sqrt{\omega} x_2) \operatorname{sech}^2(\sqrt{\omega} x_3)}{\sqrt{\omega}} & \omega \rightarrow 0 & -z x_2 \\ \{x_0, x_3\} &= -\frac{z \tanh(\sqrt{\omega} x_3)}{\sqrt{\omega}} & \omega \rightarrow 0 & -z x_3 \\ \{x_1, x_2\} &= -\frac{z \cosh(\sqrt{\omega} x_1) \tanh^2(\sqrt{\omega} x_3)}{\sqrt{\omega}} & \omega \rightarrow 0 & 0 \\ \{x_1, x_3\} &= \frac{z \cosh(\sqrt{\omega} x_1) \tanh(\sqrt{\omega} x_2) \tanh(\sqrt{\omega} x_3)}{\sqrt{\omega}} & \omega \rightarrow 0 & 0 \\ \{x_2, x_3\} &= -\frac{z \sinh(\sqrt{\omega} x_1) \tanh(\sqrt{\omega} x_3)}{\sqrt{\omega}} & \omega \rightarrow 0 & 0 \end{aligned}$$

With respect to the Minkowski limit $\omega = -\Lambda \rightarrow 0$, space coordinates do not commute and space isotropy is lost.

³A.B., I. Gutiérrez-Sagredo, F.J. Herranz, *The κ -AdS Poisson homogeneous spacetime*, preprint.

The (2+1) κ -AdS $_{\omega}$ noncommutative spacetime

The **classical r -matrix** in the (2+1) case reads ⁴

$$r = z(K_1 \wedge P_1 + K_2 \wedge P_2),$$

and the **Lie bialgebra** $(\text{AdS}_{\omega}, \delta)$ is

$$\delta(P_0) = \delta(J) = 0,$$

$$\delta(P_1) = z(P_1 \wedge P_0 - \omega K_2 \wedge J),$$

$$\delta(P_2) = z(P_2 \wedge P_0 + \omega K_1 \wedge J),$$

$$\delta(K_1) = z(K_1 \wedge P_0 + P_2 \wedge J),$$

$$\delta(K_2) = z(K_2 \wedge P_0 - P_1 \wedge J).$$

This Lie bialgebra **fulfills the coisotropy condition** with $\mathfrak{h} = \{J, K_1, K_2\}$:

$$\delta(\mathfrak{h}) \subset \mathfrak{h} \wedge \mathfrak{g}.$$

⁴A.B., F.J. Herranz, M.A. del Olmo, M. Santander, J. Phys. A **27** (1994) 1283.

Poisson-Lie group relations among spacetime x_μ group coordinates:

$$\{x_0, x_1\} = -z \frac{\tanh \sqrt{\omega} x_1}{\sqrt{\omega} \cosh^2 \sqrt{\omega} x_2} \quad \omega \rightarrow 0 \quad -z x_1$$

$$\{x_0, x_2\} = -z \frac{\tanh \sqrt{\omega} x_2}{\sqrt{\omega}} \quad \omega \rightarrow 0 \quad -z x_2$$

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Poisson–Lie group relations among spacetime x_μ group coordinates:

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The quantum AdS_ω group in ‘local coordinates’ would be the quantization of the above nonlinear PL bracket. In particular, since $\{x_1, x_2\} = 0$ we could write:

$$\begin{aligned} [\hat{x}_0, \hat{x}_1] &= -z \frac{\tanh \sqrt{\omega} \hat{x}_1}{\sqrt{\omega} \cosh^2 \sqrt{\omega} \hat{x}_2} = -z \left(\hat{x}_1 - \frac{1}{3} \omega \hat{x}_1^3 - \omega \hat{x}_1 \hat{x}_2^2 \right) + \mathcal{O}(\omega^2), \\ [\hat{x}_0, \hat{x}_2] &= -z \frac{\tanh \sqrt{\omega} \hat{x}_2}{\sqrt{\omega}} = -z \left(\hat{x}_2 - \frac{1}{3} \omega \hat{x}_2^3 \right) + \mathcal{O}(\omega^2), \\ [\hat{x}_1, \hat{x}_2] &= 0. \end{aligned}$$

OPEN PROBLEMS

- Construction of the **coisotropic PHS for AdS^{2+1}** .

- Construction of the **coisotropic PHS for AdS²⁺¹**.
- Classification of **Poisson-Lie (A)dS groups** in (3+1) dimensions.

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- The **Minkowski and (A)dS³⁺¹ PHS**: the H subgroup is $SO(3, 1)$.
The complete classification of coisotropic and Poisson subgroup Lie bialgebra structures on $SO(3, 2)$, $SO(4, 1)$ and $P(3 + 1)$.

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- Construction of **PHS of time-like worldlines**:

$$\mathfrak{h} = \{J_1, J_2, J_3, P_0\}$$

$\omega = -\Lambda$	Space of time-like worldlines $\mathbb{S}_{(2)} \equiv \{x_1, x_2, x_3, \xi_1, \xi_2, \xi_3\}$
$\omega > 0, \Lambda < 0$	$\mathbf{LAdS}^{3 \times 3} = SO(3, 2) / (SO(3) \otimes SO(2))$
$\omega = \Lambda = 0$	$\mathbf{LM}^{3 \times 3} = ISO(3, 1) / (SO(3) \otimes \mathbb{R})$
$\omega < 0, \Lambda > 0$	$\mathbf{LdS}^{2 \times 2} = SO(4, 1) / (SO(3) \otimes SO(2, 1))$

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- **Quantization of PHS** and **representation theory** of the associated spacetime algebras.

THANKS FOR YOUR ATTENTION

Quantized Space-Time

HARTLAND S. SNYDER

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(Received May 13, 1946)

It is usually assumed that space-time is a continuum. This assumption is not required by Lorentz invariance. In this paper we give an example of a Lorentz invariant discrete space-time.

for transformations from one inertial frame to another. It is usually assumed that the variables x , y , z , and t take on a continuum of values and that they may take on these values simultaneously. This last assumption we change to the following:

x , y , z , and t are Hermitian operators for the space-time coordinates of a particular Lorentz frame; the spectrum of each of the operators x , y , z , and t is composed of the possible results of a measurement of the corresponding quantity; the operators x , y , z , and t shall be such that the spectra of the operators x' , y' , z' , t' formed by taking linear combinations of x , y , z , and t , which leave the quadratic form (1) invariant, shall be the same as the spectra of x , y , z , and t .

The ten operators defined in (3) and (4) have a total of forty-five commutators. Only six of these commutators differ from the ordinary ones and these six are

$$[x, y] = (ia^2/\hbar)L_z, \quad [t, x] = (ia^2/\hbar c)M_x,$$

$$[y, z] = (ia^2/\hbar)L_x, \quad [t, y] = (ia^2/\hbar c)M_y, \quad (5)$$

$$[z, x] = (ia^2/\hbar)L_y, \quad [t, z] = (ia^2/\hbar c)M_z.$$

We see from these commutators that if we take the limit $a \rightarrow 0$ keeping \hbar and c fixed, our quantized space-time changes to the ordinary continuous space-time.